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c\_PlatformRotationY

c\_PlatformRotationX

Ball Trajectory Determination

m\_PositionXball2

m\_PositionYball2

m\_PositionZball2

Balancing Trajectory Determination

m\_PlatformPosition

Motor Control

m\_DesiredTrajectory

m\_PositionZball1

m\_PositionYball1

m\_PositionXball1

m\_CurrentTrajectory

Platform Positioning